



## Single Enclosure GPS/INS Receiver Delivers 3D Position, Velocity and Attitude Solution

### Benefits

Continuous positioning

Easy to integrate

Minimizes import/export issues

Withstands harsh environments

Proven OEMV® technology

### Features

Fiber optic gyros and MEMS accelerometers

SBAS, L-band and RTK support

100 Hz raw data and solution

Wheel sensor input for ground applications

### GPS+INS Solution Unlike Any Other

NovAtel's SPAN (Synchronous Position, Attitude and Navigation) technology brings together two different, but complementary technologies: GPS positioning and inertial navigation. The absolute accuracy of GPS positioning and the stability of inertial measurement unit (IMU) gyro and accelerometer measurements are tightly coupled to provide an exceptional 3D navigation solution that is stable and continuously available, even through periods when GPS signals are blocked.

### SPAN-CPT Overview

SPAN-CPT is powered by NovAtel's world-class, professional-grade OEMV GPS technology. Solution accuracy can be varied by application by enabling different positioning modes including SBAS, L-band (OmniSTAR and CDGPS) and RTK.

The IMU components, integrated within the SPAN-CPT enclosure, are comprised of fiber optic gyros (FOG) and micro electrical mechanical systems (MEMS) accelerometers and offer the best price/performance available. FOGs offer exceptionally long life and stable performance compared with other similar gyro technologies.

### SPAN-CPT Advantages

The tight coupling of the GPS and IMU measurements delivers the most satellite observations and the most accurate, continuous solution possible. Further, SPAN-CPT is comprised entirely of commercial components, which means cross-border difficulties involved with traditional GPS/INS systems are greatly minimized.

To learn more about SPAN technology go to [www.improveyourgps.com](http://www.improveyourgps.com)

If you require more information about our SPAN products, visit [improveyourgps.com](http://improveyourgps.com)



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**SPAN System Performance<sup>1</sup>**

<b>Horizontal Position Accuracy (RMS)</b>	
Single Point L1	1.8 m
Single Point L1/L2	1.5 m
SBAS	0.6 m
CDGPS	0.6 m
DGPS	0.45 m
OmniSTAR	
VBS	0.7 m
XP	0.15 m
HP	0.1 m
RT-20™	0.2 m
RT-2™	1 cm+1 ppm
<b>Velocity Accuracy</b>	<b>0.02 m/s RMS</b>
<b>Attitude Accuracy</b>	
Roll	0.05° RMS
Pitch	0.05° RMS
Azimuth	0.1° RMS
<b>Data Rates</b>	
GPS Measurement	5 Hz
GPS Position	5 Hz
IMU Measurement	100 Hz
INS Solution	Up to 100 Hz
Time Accuracy <sup>2</sup>	20 ns RMS
Maximum Velocity <sup>3</sup>	515 m/s

**IMU Performance**

Gyro Technology	FOG
Gyro Output Range	±375°/s
Gyro Bias	±20°/hr
Gyro Bias Stability	±1°/hr
Gyro Scale Factor	1500 ppm
Angular Random Walk	0.0667°/√hr (max)
Accelerometer Range	±10 g
Accelerometer Bias	±50 mg
Accelerometer Bias Stability	±0.75 mg
Accelerometer Scale Factor	4000 ppm

**Physical and Electrical**

<b>Dimensions</b>	<b>152 x 168 x 89 mm</b>
<b>Weight</b>	<b>2.36 kg</b>
<b>Power</b>	
Power Consumption	15 W Max
Input Voltage	+9 to +18 VDC
<b>Antenna Port Power Output</b>	
Output Voltage	+5 VDC
Maximum Current	100 mA
<b>Input/Output Connectors</b>	
Power and I/O	MIL-DTL-38999 Series 3
Antenna Input	TNC Female

**Communication Ports**

RS232 UART COM	2
USB Device	1
CAN	1
Event Input Trigger	1
Configurable PPS	1

**Environmental**

Temperature	
Operating	-40°C to +65°C
Storage	-50°C to +80°C
Humidity	95% non-condensing
Waterproof	MIL-STD-810F, 506.4, Procedure I
Vibration (operating)	MIL-STD-810F, 6 g RMS
Shock (operating)	7 g
Shock (non-operating)	MIL-STD-810F, 60 g

**Regulatory**

Emissions	FCC Part 15, Class B EN 55022, Class B
Immunity	EN 55024
Safety	EN 609050-1

**Included Accessories**

- Combined I/O and Power Cable

**Optional Accessories**

- GPS-700 series antennas (dual frequency required)
- Antcom antennas (dual frequency required)
- RF cables – 5, 10 and 30 m lengths

For additional GNSS Specifications, please see:  
[novatel.com/Documents/Papers/OEMV3.pdf](http://novatel.com/Documents/Papers/OEMV3.pdf)

**Performance During GNSS Outages<sup>4</sup>**

Outage Duration	Position Error (m)		Velocity Error (m/s)		Attitude Error (degrees)		
	Horizontal	Vertical	Horizontal	Vertical	Roll	Pitch	Yaw
10 s	0.19	0.14	0.04	0.03	0.01	0.01	0.02
30 s	1.50	0.70	0.10	0.05	0.02	0.02	0.03
60 s	6.00	2.00	0.25	0.20	0.03	0.03	0.05



Version 1a - Specifications subject to change without notice.

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Printed in Canada. D12768

SPAN-CPT September 2009

For the most recent details of this product:  
[novatel.com/Documents/Papers/SPAN-CPT.pdf](http://novatel.com/Documents/Papers/SPAN-CPT.pdf)

<sup>1</sup> Typical values. Performance specifications subject to GPS system characteristics, US DOD operational degradation, ionospheric and tropospheric conditions, satellite geometry, baseline length, multipath effects and the presence of intentional or unintentional interference.

<sup>2</sup> Time accuracy does not include biases due to RF or antenna delay.

<sup>3</sup> Export licensing restricts operation to a maximum of 515 metres/second.

<sup>4</sup> RMS, incremental error growth from steady-state accuracy. Computed with respect to full GPS, RTK trajectory.

